

Question #1.

Automobile  $A$  is traveling along a straight highway, while automobile  $B$  is moving along a circular exit ramp having a radius of 150 m as illustrated in Figure 1. The speed of  $A$  is being increased at the rate of  $1.5 \text{ m/s}^2$  and the speed of  $B$  is being decreased at the rate of  $0.9 \text{ m/s}^2$ . For the position shown, determine:

- the velocity of  $A$  relative to  $B$ , and
- the acceleration of  $A$  relative to  $B$ .

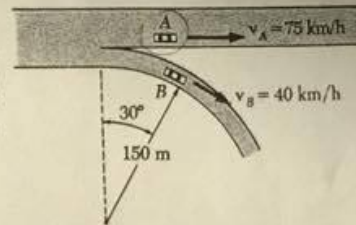


Figure 1.

Question #2.

After rolling down a  $20^\circ$  incline a sphere, having a mass of  $0.03 \text{ kg}$ , has a velocity of  $\vec{v}_0$  at point  $A$ , as illustrated in Figure 2. Determine the range of values of  $|\vec{v}_0|$  for which the sphere will enter the horizontal pipe  $BC$ , having a diameter of  $0.5 \text{ m}$ , shown.

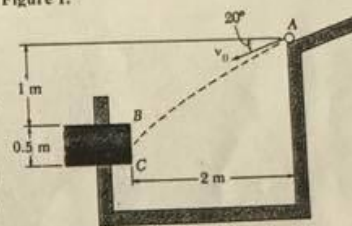


Figure 2.

Question #3.

The mechanism illustrated in Figure 3 is used at a local pumpkin processing facility to generate high quality jack-o-lanterns. Rod  $BE$  is the input driving rod to the system and point  $A$  will hold a knife edge used for carving pumpkins. Knowing that at the instant shown the velocity of collar  $D$  is  $1.33 \text{ m/s}$  downwards, determine, using only an analytical method, the following:

- the angular velocity of rod  $BE$ , and
- the velocity of point  $A$ .

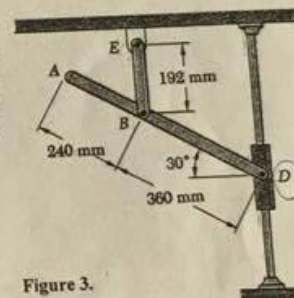


Figure 3.

Note:

$$\vec{a} = \frac{dv}{dt} \cdot \vec{u}_t + \frac{v^2}{\rho} \cdot \vec{u}_n$$

$$\rho = \frac{\left(1 + \left(\frac{dy}{dx}\right)^2\right)^{3/2}}{|d^2y/dx^2|}$$

$$x = x_0 + v_{x0} \cdot t + \frac{a_x \cdot t^2}{2}$$

$$v_x = v_{x0} + a_x \cdot t$$

$$v_2^2 = v_1^2 + 2 \cdot a \cdot s$$

$$\theta = \theta_0 + \omega_0 \cdot t + \frac{\alpha \cdot t^2}{2}$$

$$\omega_2 = \omega_1 + \alpha \cdot t$$

$$\omega_2^2 = \omega_1^2 + 2 \cdot \alpha \cdot \Delta \theta$$

$$\vec{a}_A = \vec{a}_B + \vec{a}_{A/B}$$

$$\vec{a}_A = \vec{a}_B + \vec{\alpha} \times \vec{r}_{A/B} + \vec{\omega} \times (\vec{\omega} \times \vec{r}_{A/B})$$

$$\vec{v}_A = \vec{v}_B + \vec{\omega} \times \vec{r}_{A/B}$$

$$\vec{v}_A = \vec{v}_B + \vec{v}_{A/B}$$

### Question #1.

A soccer ball is kicked by a player at ground level with an initial speed of 8 m/s at an angle of  $40^\circ$  from the horizontal. For 0.25 seconds after the ball was kicked, determine:

- the horizontal and vertical components of the ball's acceleration, and
- the normal and tangential components of the ball's acceleration.

### Question #2.

It is known that the static-friction force between the small block  $B$  and the plate, both shown in **Figure 1**, will be exceeded and that the block will start sliding on the plate when the total acceleration of the block reaches  $4 \text{ m/s}^2$ . If the plate starts from rest at  $t = 0 \text{ s}$  and is accelerated at the constant rate of  $5 \text{ rad/s}^2$ , determine the time  $t$  and the magnitude of the angular velocity of the plate when the block starts sliding.

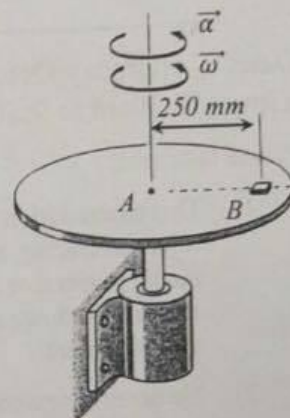


Figure 1

### Question #3.

The hydraulic cylinder  $CD$  is welded to an arm which rotates clockwise about  $A$  at the constant rate  $\bar{\omega} = 2.4 \text{ rad/s}$  in the direction shown in **Figure 2**. Knowing that in the position shown rod  $BE$  is being moved to the right at a constant rate of  $375 \text{ mm/s}$  with respect to the cylinder, determine for the instant shown, (a) the velocity of point  $B$ , and (b) the acceleration of point  $B$ .

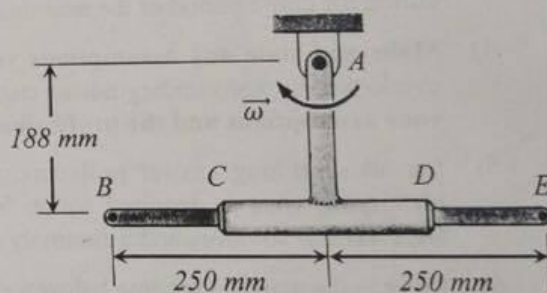


Figure 2.

Note:  $a_t = \frac{dv}{dt}$ ,  $a_n = \frac{v^2}{\rho}$

$$\vec{a} = \frac{dv}{dt} \cdot \vec{u}_t + \frac{v^2}{\rho} \cdot \vec{u}_n$$

$$\rho = \frac{\left(1 + \left(\frac{dy}{dx}\right)^2\right)^{3/2}}{\left| \frac{d^2y}{dx^2} \right|}$$

$$x = x_0 + v_{x0} \cdot t + \frac{a_x \cdot t^2}{2}$$

$$v_x = v_{x0} + a_x \cdot t$$

$$v_2^2 = v_1^2 + 2 \cdot a \cdot s$$

$$\theta = \theta_0 + \omega_0 \cdot t + \frac{\alpha \cdot t^2}{2}$$

$$\omega_2 = \omega_1 + \alpha \cdot t$$

$$\omega_2^2 = \omega_1^2 + 2 \cdot \alpha \cdot \Delta \theta$$

$$\vec{a}_A = \vec{a}_B + \vec{a}_{A/B}$$

$$\vec{a}_A = \vec{a}_B + \vec{\alpha} \times \vec{r}_{A/B} + \vec{\omega} \times (\vec{\omega} \times \vec{r}_{A/B})$$

$$\vec{a}_A = \vec{a}_B + \vec{\alpha} \times \vec{r}_{A/B} + \vec{\omega} \times (\vec{\omega} \times \vec{r}_{A/B}) + 2 \cdot \vec{\omega} \times (\vec{v}_{A/B})_{xyz} + (\vec{a}_{A/B})_{xyz}$$

$$\vec{v}_A = \vec{v}_B + \vec{\omega} \times \vec{r}_{A/B}$$

$$\vec{v}_A = \vec{v}_B + \vec{\omega} \times \vec{r}_{A/B} + (\vec{v}_{A/B})_{xyz}$$

$$I_x = I_x + A \cdot d^2$$